



**ETH** Shaping the future

# *Der Roboter bringt viel, aber nicht alles*

Prof. Dr. Roland Siegwart

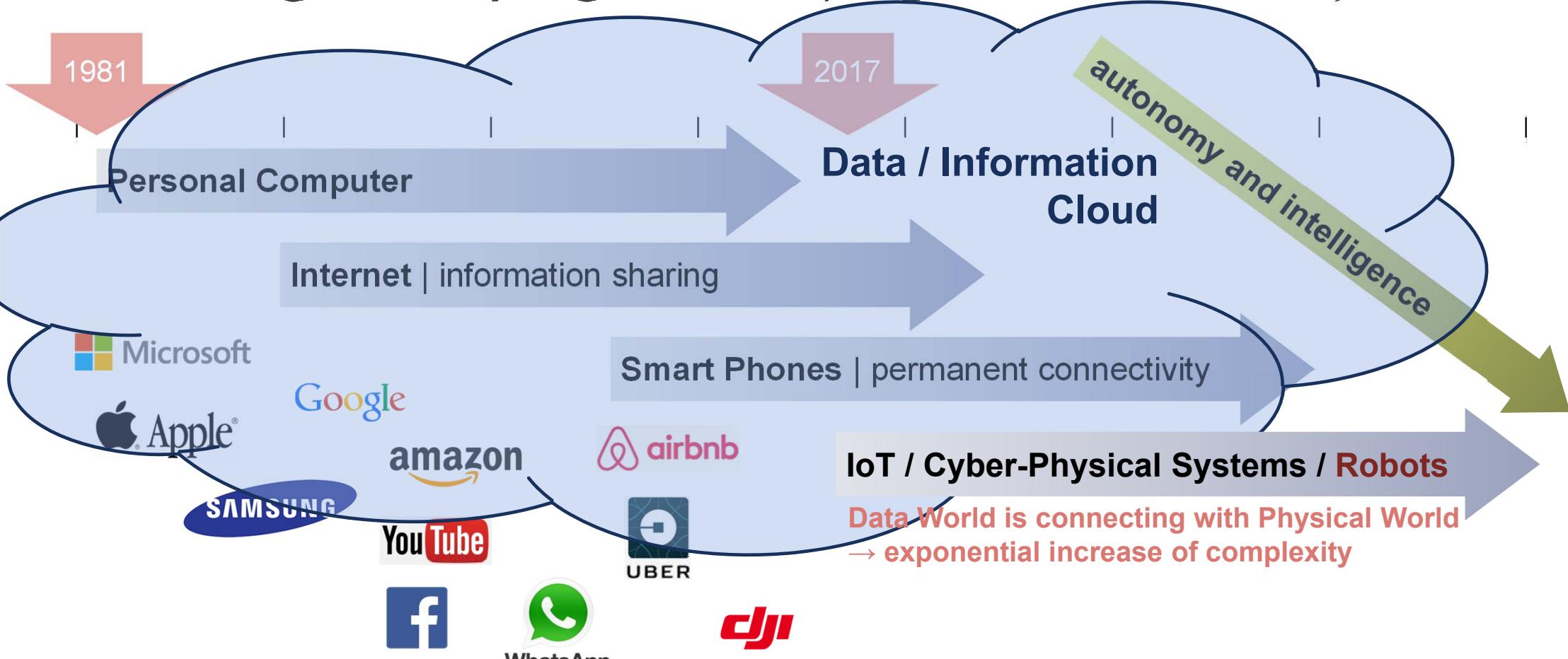
[www.asl.ethz.ch](http://www.asl.ethz.ch)

[www.wysszurich.ch](http://www.wysszurich.ch)

**swiss  
BoardForum | event**  
sharing experience

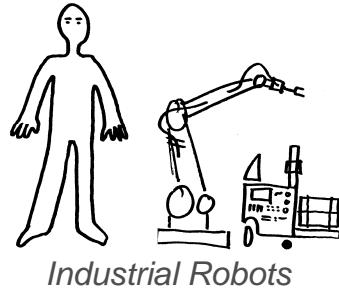
Kursaal Bern, 20. Juni, 2018

# Technologies disrupting services | digitalization / industry 4.0

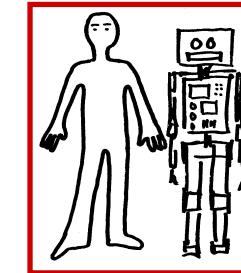


# Nächste Generation von Robotern

| mobil, verbunden, intelligent, adaptiv und unter uns



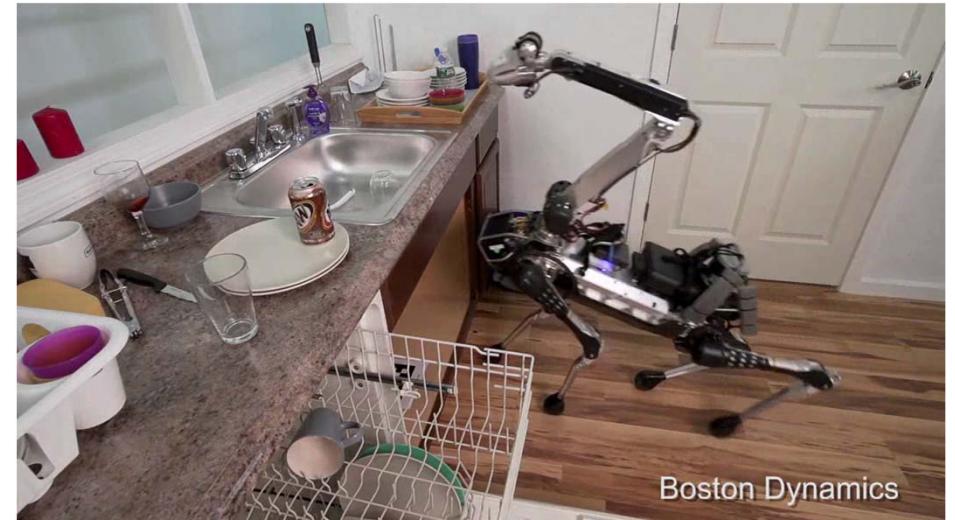
Industrial Robots



Service Robots



<https://www.youtube.com/watch?v=SeloQy0oXjI>



<https://www.youtube.com/watch?v=tf7IEVTDjng>

## Serviceroboter | die Herausforderungen

- Roboter müssen mit *unsicherer* und nur *teilweise verfügbarer multimodaler Information* umgehen können.
- Roboter müssen *sehen, spüren* und *verstehen* können.
- Roboter müssen *taktil* mit der Umgebung interagieren können  
→ («soft robots» mit Kraftreglung)
- Roboter müssen *intuitiv programmierbar* sein
- Roboter müssen *lern- und anpassungsfähig* sein  
→ **Um das zu erfüllen, braucht es Künstliche Intelligenz, aber auch neue Sensoren, Aktoren und Roboterkonzepte**



**Willow Garage**

50x speed

<https://www.youtube.com/watch?v=gy5g33S0Gzo>



Roland Siegwart 20.06.2018 8

## Service Robots

– wheeled and walking robots for challenging tasks

**BeachBot** (with Disney) – developed by students

| the beach artist

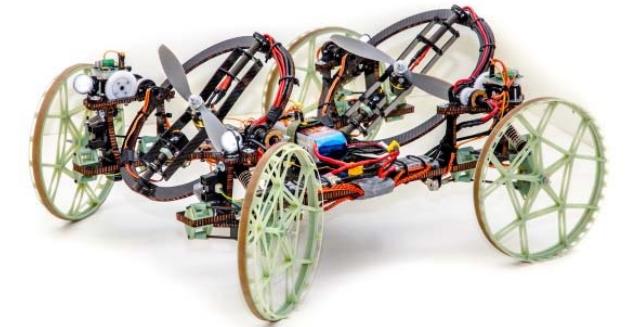
<https://www.youtube.com/watch?v=eBRrQBPtak>



**Vertigo** – developed by students

| the ultimate wall climber

<https://www.youtube.com/watch?v=KRYT2kYbgo4>



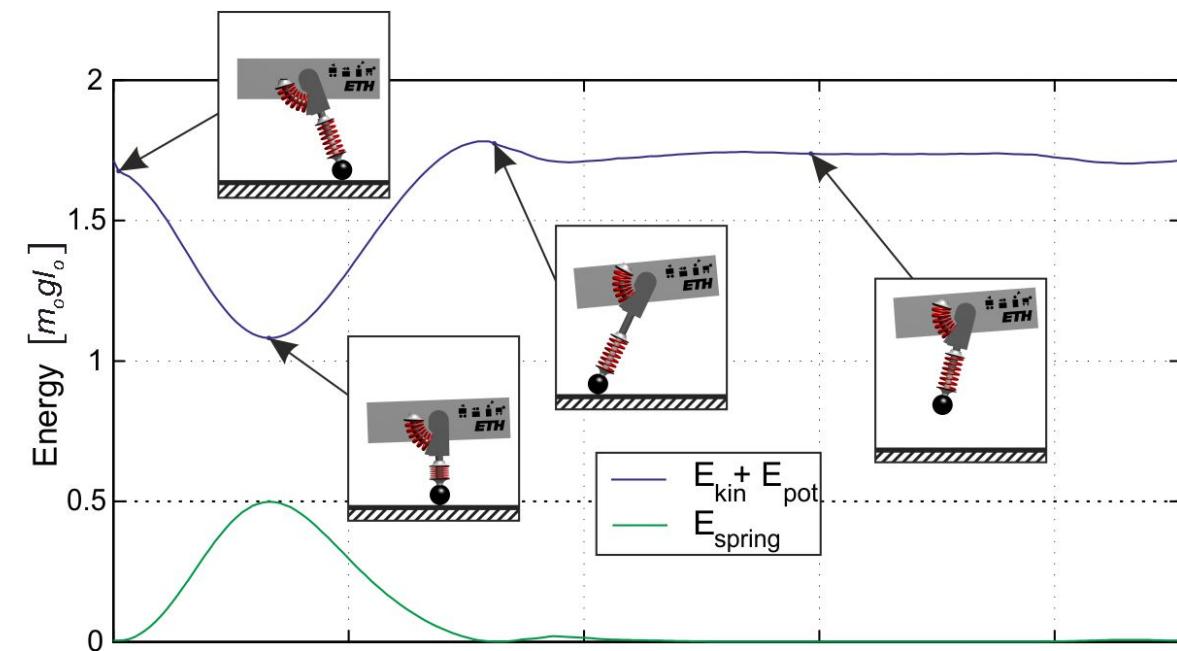
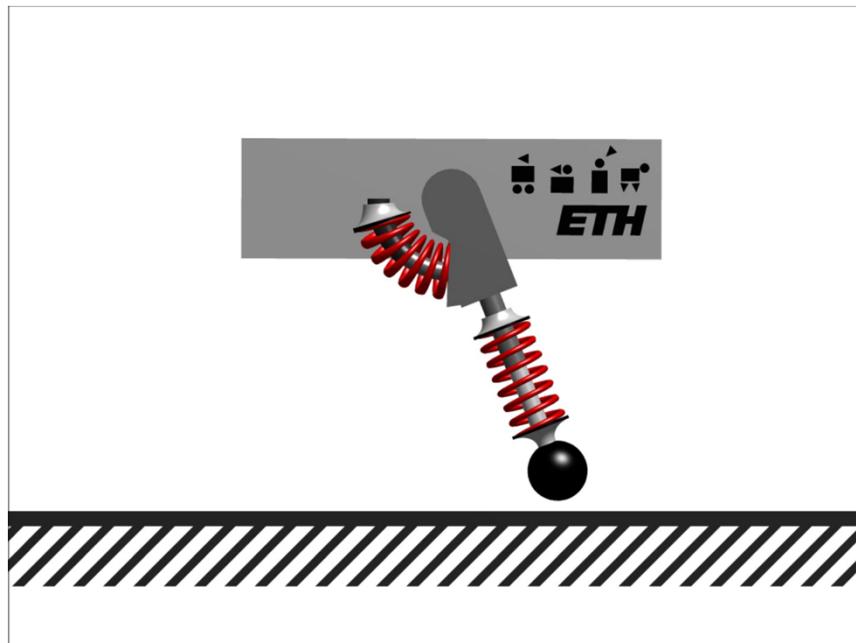
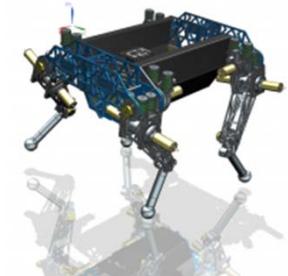
# Efficient Walking and Running |

## what nature evolved (Extreme Jumpy Dog)



- <http://www.youtube.com/watch?v=Jql6TSyudFE>

# Efficient Walking and Running | serial elastic actuation



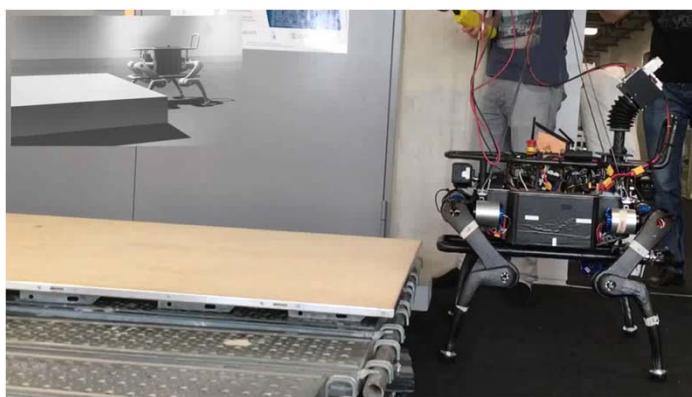
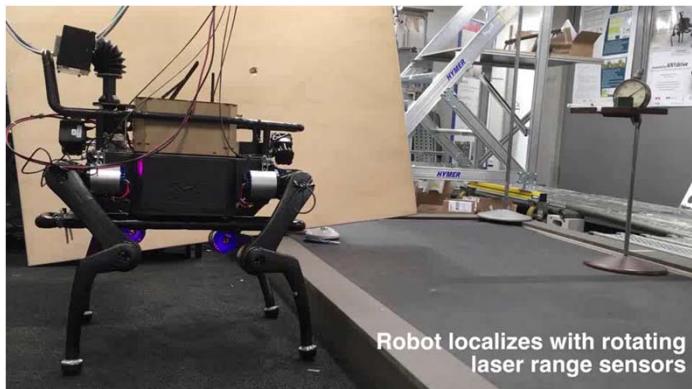
<https://www.youtube.com/watch?v=6igNZiVtbxU>

# ANYmal

## Combining dynamic motion skills with large mobility



**RSL**  
Robotic Systems Lab  
Prof. Marco Hutter



## Service Robots – flying robots for challenging tasks

**wingtra** – developed by students

| the VTOL UAV

<https://www.youtube.com/watch?v=QADvPDWtgFU>



| 81 hours non-stop in summer 2015

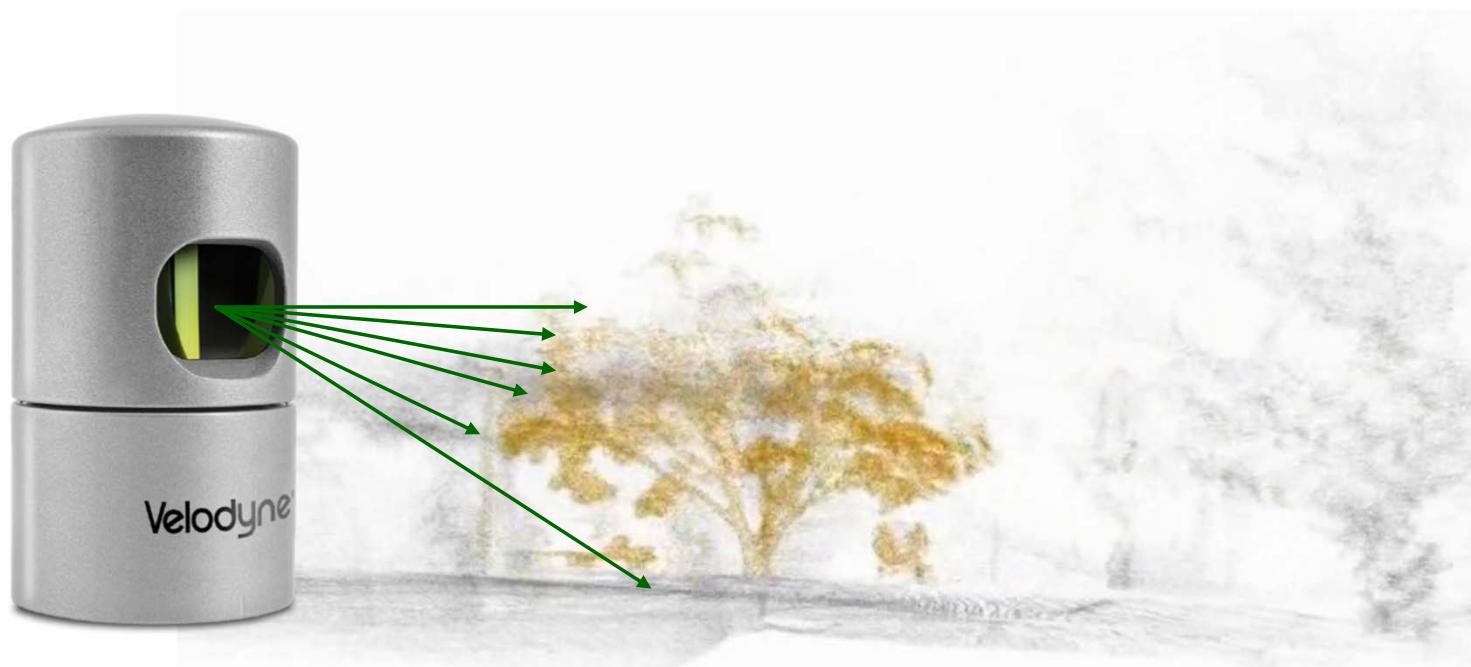
| 5.64 m, 6.2 kg

[https://www.youtube.com/watch?v=8m4\\_NpTQn0E](https://www.youtube.com/watch?v=8m4_NpTQn0E)

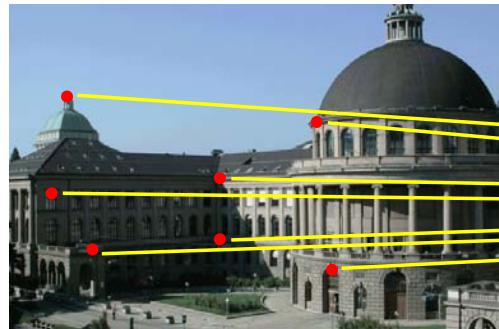
[https://www.youtube.com/watch?v=wyS6W1t\\_ryQ](https://www.youtube.com/watch?v=wyS6W1t_ryQ)



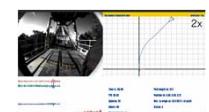
## “Sehen” | Laser-basierte 3D Pläne



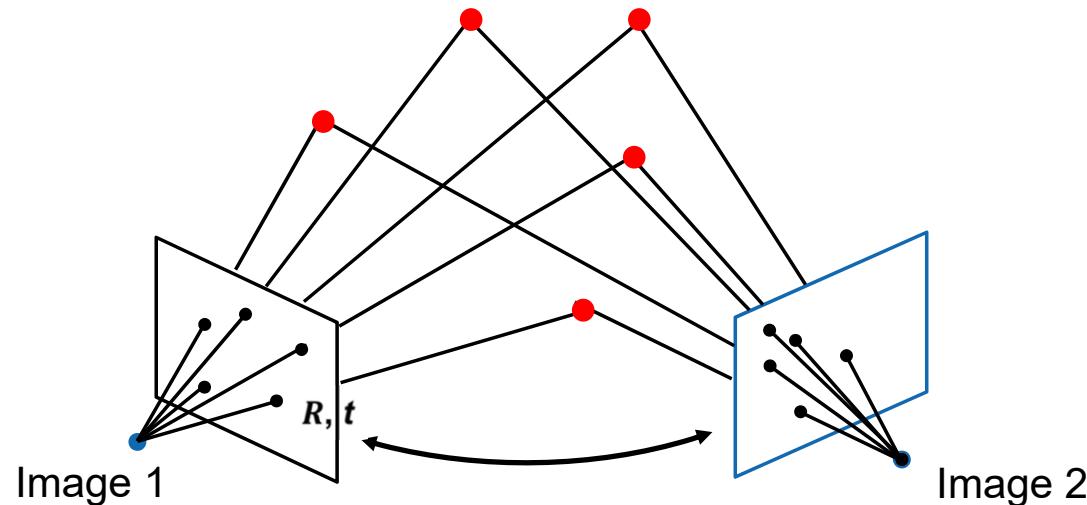
## “Sehen” | Bewegungsschätzung mit Kamera und Inertialsensor (IMU)



Google  
Project Tango

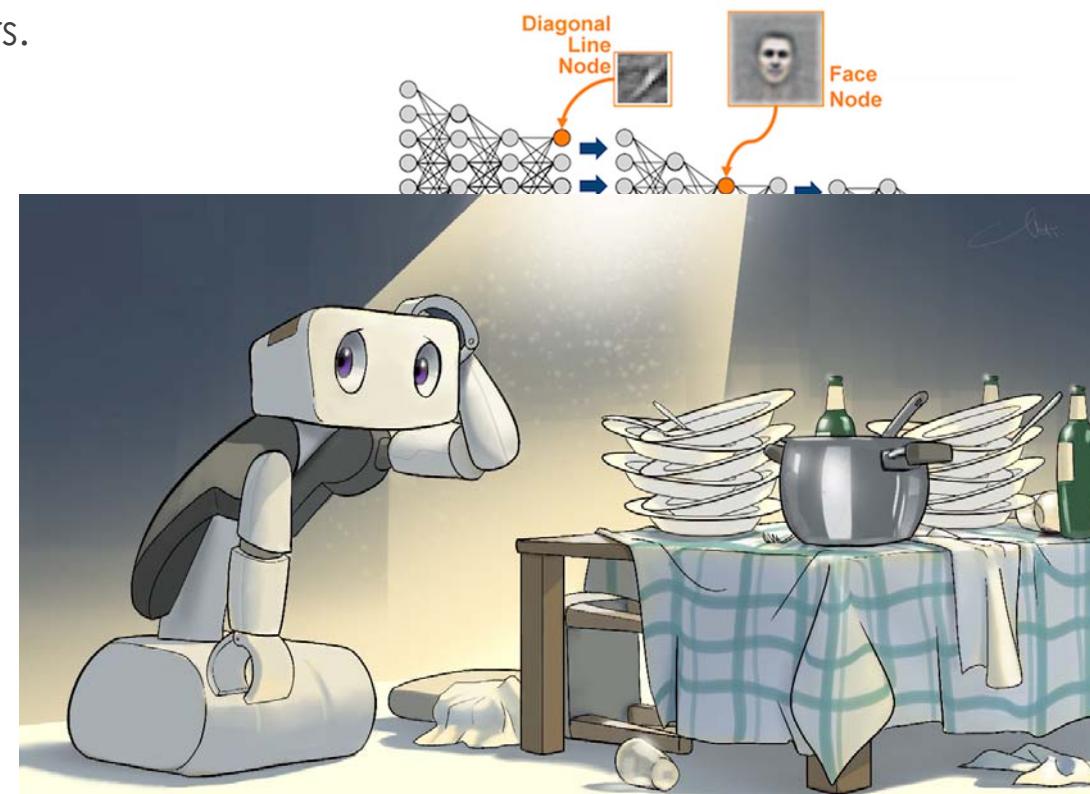
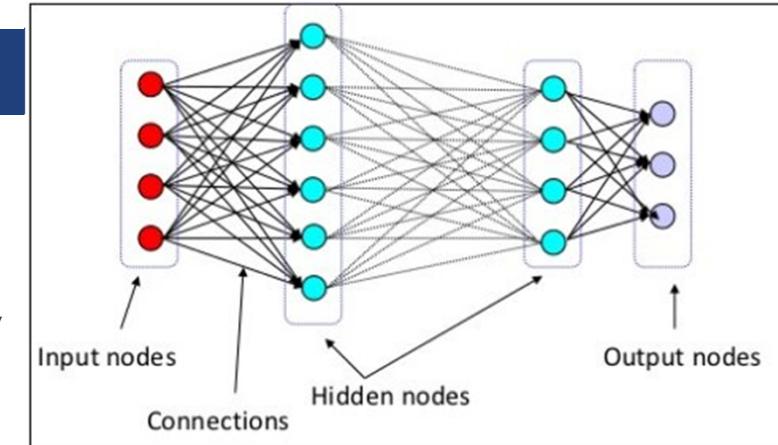


<https://www.youtube.com/watch?v=yvgPrZNp4So>



# AI-Example: Deep Learning for Robotics

- Key Idea: mimic behavior of neurons in a human brain in a very simplified way.
- Deep learning methods learn an unknown function from observing numerous exemplary input/output pairs.
- Examples
  - Recognizing object types in images.
  - Recognizing words in a voice recording.
  - Recommending products based on past purchases.
- Challenges involve the generation of a big amount of training data and tackling high computational burden.
  - how to generalize from low amount of data ?
  - how to learn from real world interactions?
  - how to learn from multimodal data?
  - how to learn semantics and to understand?
- **Narrow AI ↔ General AI**



# Collaborative Visual-Inertial Navigation | teach and repeat



A Google Tango tablet is used to teach the path of an inspection mission.



<https://www.youtube.com/watch?v=pDIQxsOrgI4>

## Autonomous Cars Today | cameras (lane tracking, ...) → no map

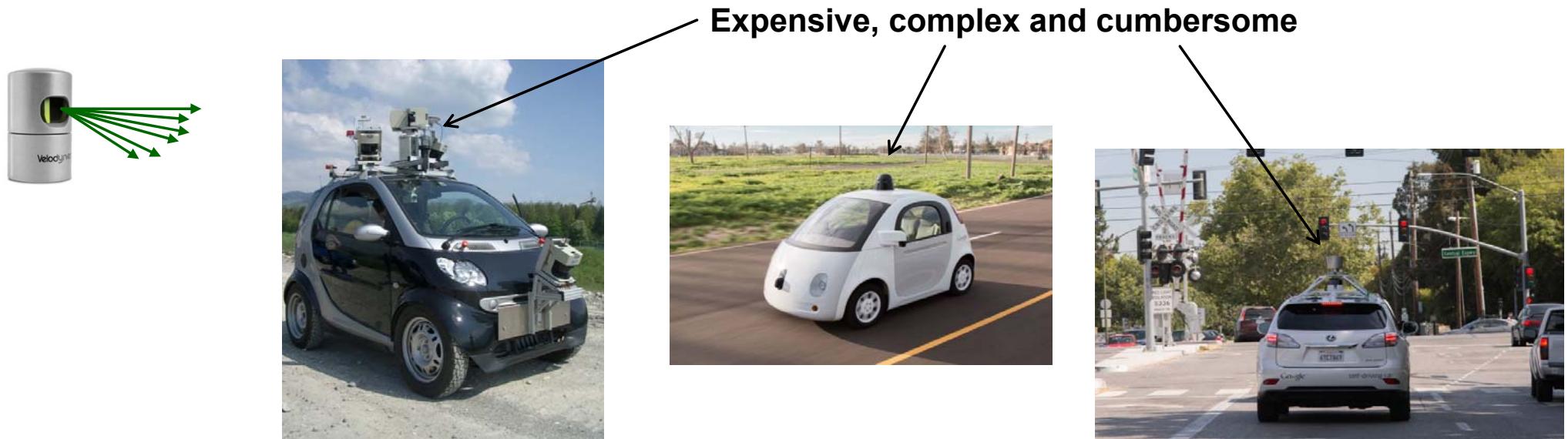


- Detection and tracking of ...
  - Lanes,
  - street signs,
  - other cars,
  - ...

<https://www.youtube.com/watch?v=aGW4nRzx8lw>



Today | 3D laser sensors → map based

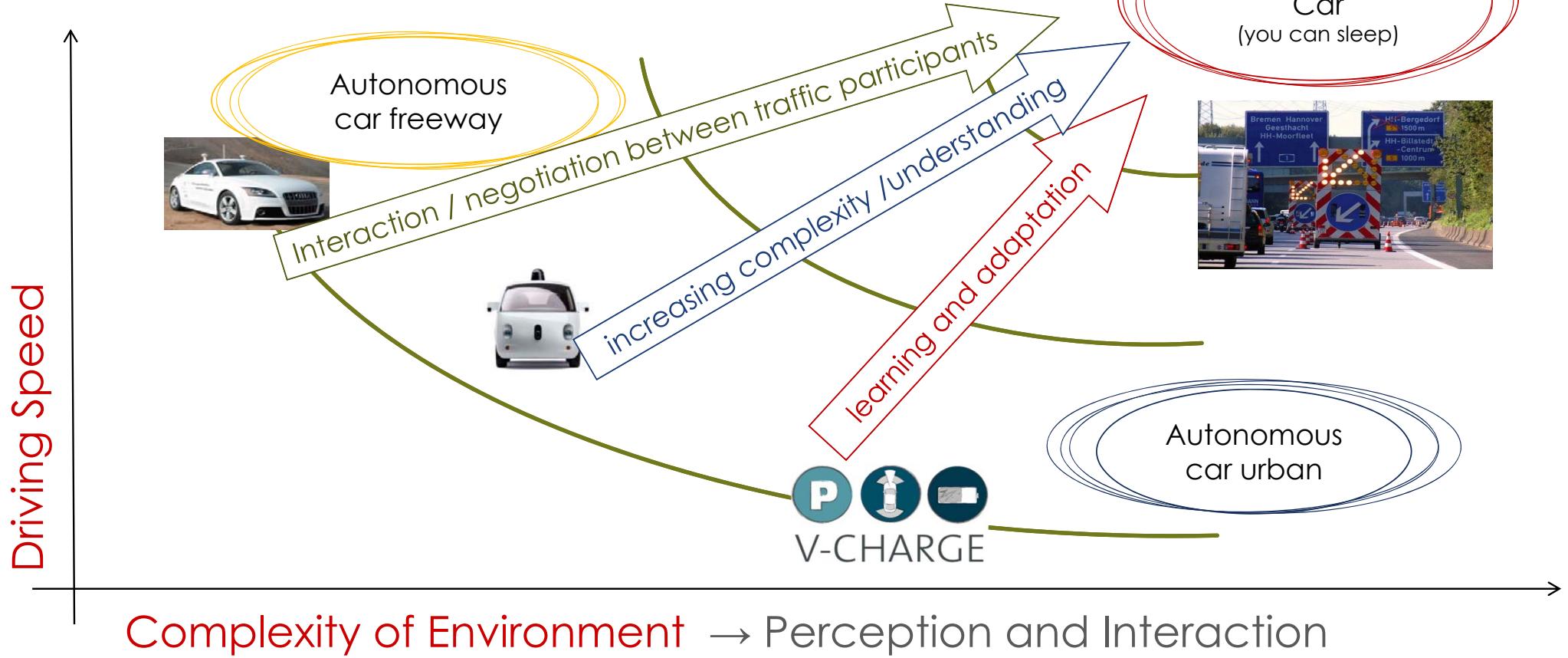


- Google Self-Driving Car Project (status summer 2015)
  - > 20 vehicles in use
  - > 2,7 mio km, 1.5 mio km in autonomous mode
  - > 11 accidents
    - No people insured
    - Non of them caused by car control algorithm



<https://www.youtube.com/watch?v=eJCR2TaeSFc>

# Autonomous Cars | roadmap

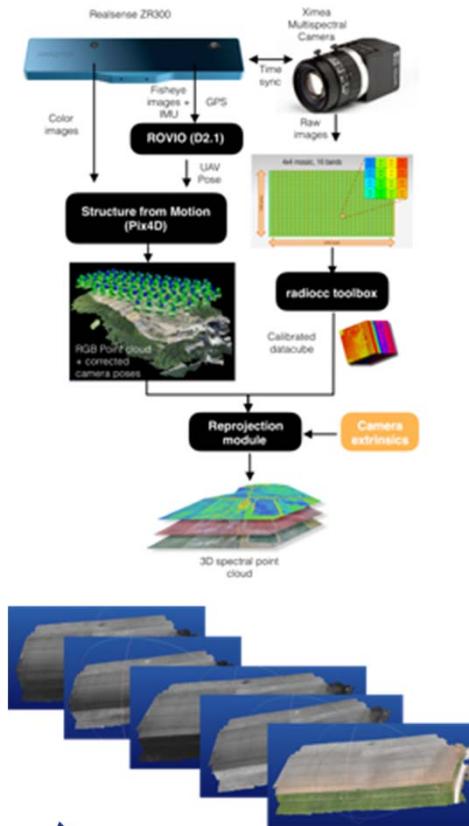


## Autonomous Cars | a bright future without traffic jams



# Flourish

## Spatio-Temporal Spectral Environment Modeling



<https://youtu.be/5f1Etfw76Qc>

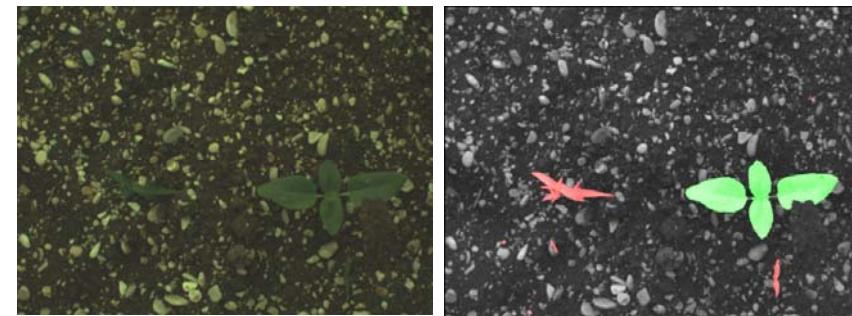
## Autonomous UAV landing



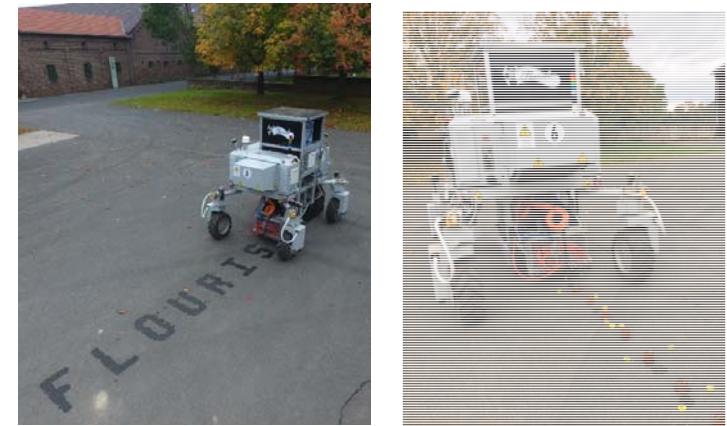
## UAV onboard weed detection



## Weed classification on UGV (Sunflower ~95% acc.)



## Automated spraying and stamping



# Roboter auf der Baustelle – NCCR Digital Fabrication



*Complexity  
of Services*

Tactile  
Manipulation

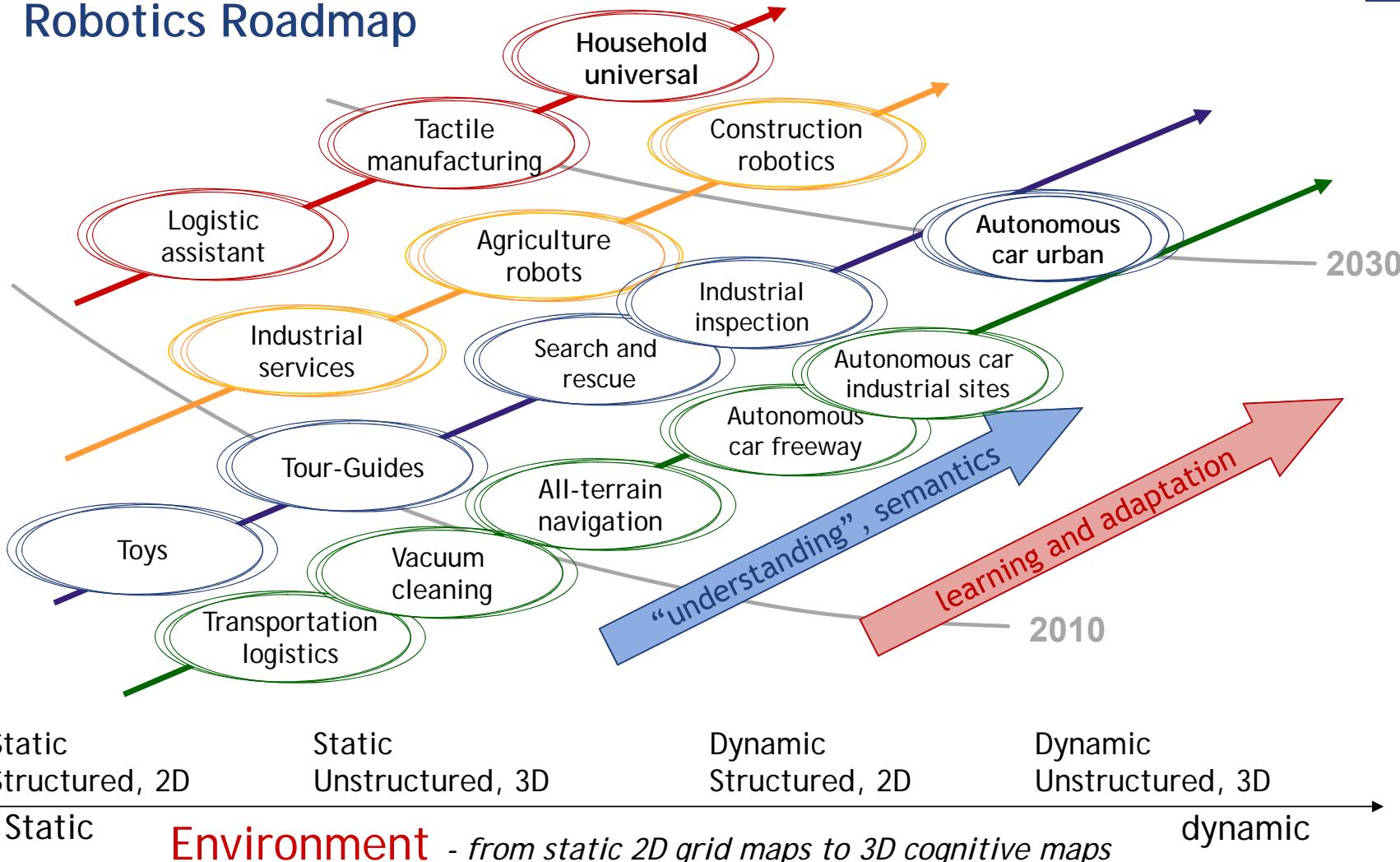
Mobile  
Manipulation

Advanced  
Interaction

Autonomous  
Navigation

**Actions** - from simple motion to complex interaction

## Robotics Roadmap



# Switzerland | a melting pot for robotics technology

## Initiatives



## Spin-offs (\* ASL)



\*



## Industrial Collaborations (ASL)



## Take Home Message

- Ja, Robotik boomte
  - ... es braucht aber noch viel F&E um diese komplexen Systeme auf den Markt zu bringen.
- Ja, Europa und speziell die Schweiz hat das Potential diesen wichtigen Markt zu erobern und somit nachhaltig Arbeitsplätze zu schaffen. Es geht um:
  - Hervorragende Forschung und grossartige Talente
  - Präzisionsmechanik und Künstliche Intelligenz
  - Innovation und Unternehmertum
- Für die Skalierung von Robotik-Technologie und Startups brauchen wir Talente, mehr **Risikobereitschaft und langfristig ausgerichtetes Risikokapital (> 10 Jahre)**

